

ATMOS B1 Lidar

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A lidar for ATOMS B1 should be an improved one of the MDS lidar, which will be launched in 2001. Main objective of the MDS lidar is to observe top height and thickness of cirrus cloud form space. Objectives of ATOMS B1 Lidar are

- (1) improvement of accuracy of the cirrus cloud thickness by adding capability for estimation multiple scattering (multi- FOV receiver, D.L.Hutt et al., 1994),
- (2) depolarization measurement of the cirrus cloud and aerosol in nighttime,
- (3) daytime tropospheric aerosol measurement.

It is believed that (1) and (2) will be performed by increasing the average power in one order magnitude.

The tentative lidar parameters of the MDS lidar is, as follows.

Laser wavelength : λ	1053nm	527nm	(1053nm)
output energy : E	90mJ	4.4mJ	(50mJ)
repetition : (rep.)	100Hz		(100Hz)
average power : $W=Ex(rep.)$	9W		(5W)
divergence : θ_t	0.15mrad		(0.1mrad)
Receiver			
Telescope : A	1m diameter		(1m diameter)
FOV : θ_r	0.19mrad		(0.1mrad)
Bandwidth : $\Delta\lambda$	0.3nm		(0.1nm)
optical efficiency : T_0	0.4		(0.5)
detector	Si-APD		(Si-APD)
quantum efficiency : η	0.36		(0.3)

Design of the MDS lidar is based on feasibility studies done by a committee for space borne laser radar, which was co-chaired by Prof.Kobayashi of Fukui university and Dr.Sasano of NIES/EA from 1991 to 1994 (final report in Japanese is available from NIES). However, lidar parameters of MDS lidar are slightly difference from those parameter discussed at the feasibility studies of the committee. The lidar parameter discussed at the committee are shown at right column in the table. Signal- Noise ratio (S/N) is shown in Fig.1 (Fig.4.2.3 of the final report). Error $\delta\beta_a$ of the backscattering coefficient β_a is

$$\delta\beta_a = \frac{\beta_a}{\sqrt{m} \left(\frac{S}{N}\right)} \quad (1)$$

where m is for averaging number of data of Fig.1. If the S/N (Day/Surface) in Fig.1 would increase one order and m were taken to be ~~50~~ ^{10⁴} (horizontal resolution ~~50m~~ ^{1.5x10⁴} ~~5km~~ ^{75km}),

β_a can be determined to be $(2.0 \pm 0.3) km^{-1} sr^{-1}$ at a height of 5km as the aerosol backscattering profile is assumed as Fig.2. The backscattering profile is correspond to aerosol optical depth of 0.06 as the scattering parameter is 50.

The S/N for daytime observation is proportional to the following factor, (S/N)factor,

$$\left(\frac{S}{N}\right) \propto (S/N)factor = \frac{W}{\theta_r \sqrt{\Delta\lambda T_0}} \quad (2)$$

where other lidar parameters are selected as the same values of the table since they are usually so difficult to be improved. The values of the (S/N)factor of the feasibility lidar and the MDS lidar are

Feasibility Lidar	224 , //1
MDS lidar	129 , 52

The S/N of the tentative MDS lidar is almost half of the S/N shown in Fig.2 since the bandwidth of the receiver is 0.3nm.

Use of the Fabry-Perot etalon is the most important to increase the S/N of the daytime observation one order magnitude. According to the Instrument Panel Report of LASA (R.J., Curran, 1987), the bandwidth and optical efficiency of the Fabry-Perot etalon are

Bandwidth : $\Delta\lambda$	0.01nm
optical efficiency : T_0	0.2,

and (S/N)factor ~~2012~~ ⁴⁰²

where $W=9$, which is the same one as the MDS lidar. When the average power is increased one order magnitude to 90, (S/N)factor becomes bigger in ~~two order~~ ^{one order} magnitude and the horizontal resolution is increased to ~~50~~ ⁷⁵km ($m \approx 8$). It is believed that the laser of 90 W average power would be realized to be increased the repetition ratio (1k Hz) in one order magnitude.

We would like to conclude that the most important issue of the ATMOS B1 Lidar development is the use of the narrow band Fabry-Perot etalon.

References

- R.J.Curran: "LASA (lidar Atmospheric Sounder and Altimeter; Instrument Panel Report for the Earth Observing System", EOS Instrument Panel Report IIg(1987)
D.L.Hutt, L.R.Bissonnette and L.Durand: "Multiple field of view lidar, returns from atmospheric aerosols", Appl.Opt.,**33**,2338-2348(1994).
Y.Sasano and T.Kobayasi:"Feasibility study on space lidars for measuring global atmospheric environment No.4, Final Report:",F-82-'95/ NIES(1995).

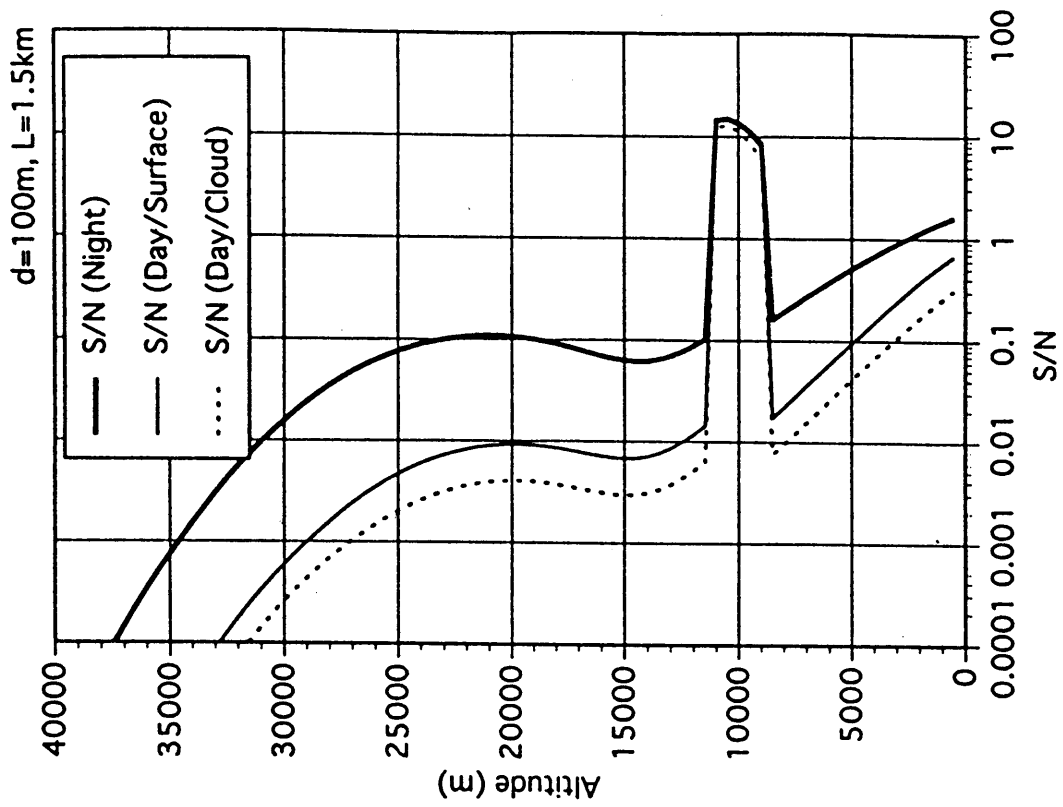


Fig.1 Signal to Noise ratio of the feasibility lidar.

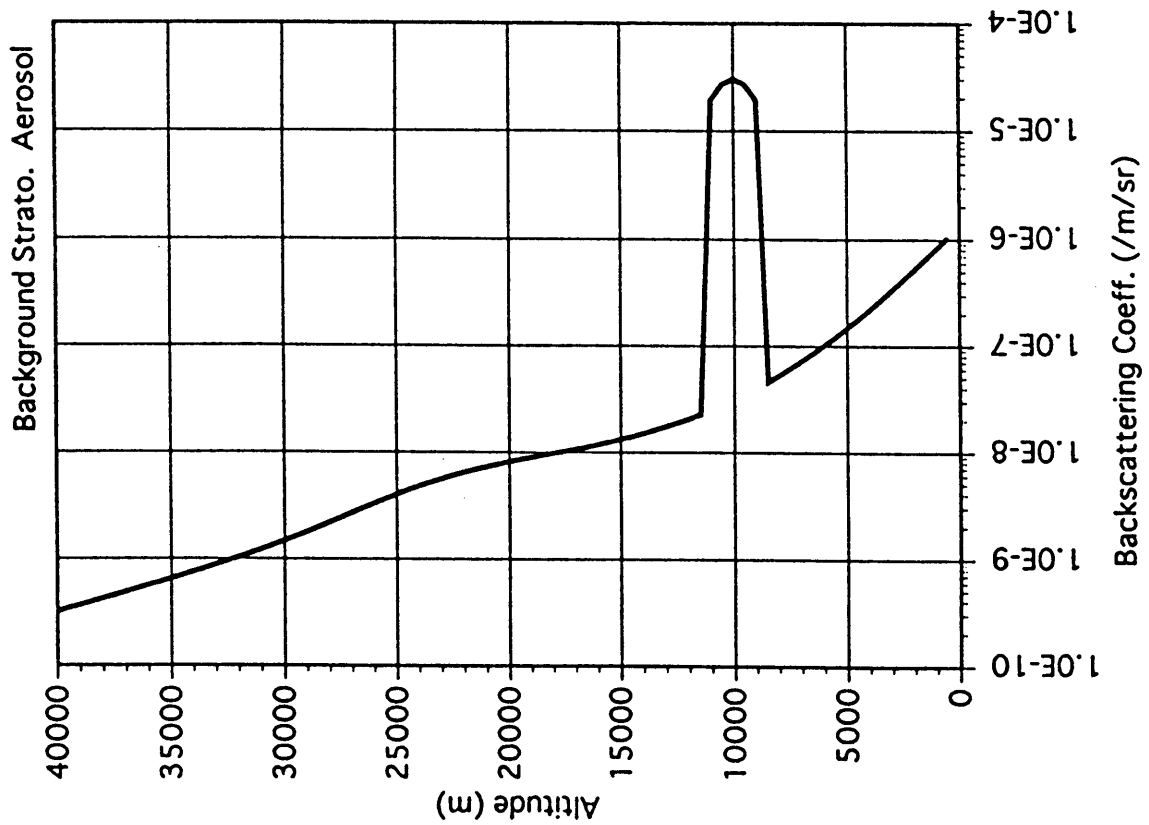


Fig.2 Backscattering profile to simulate the feasibility lidar.

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Main objective of the MDS lidar

Observation of top height and thickness
of cirrus cloud

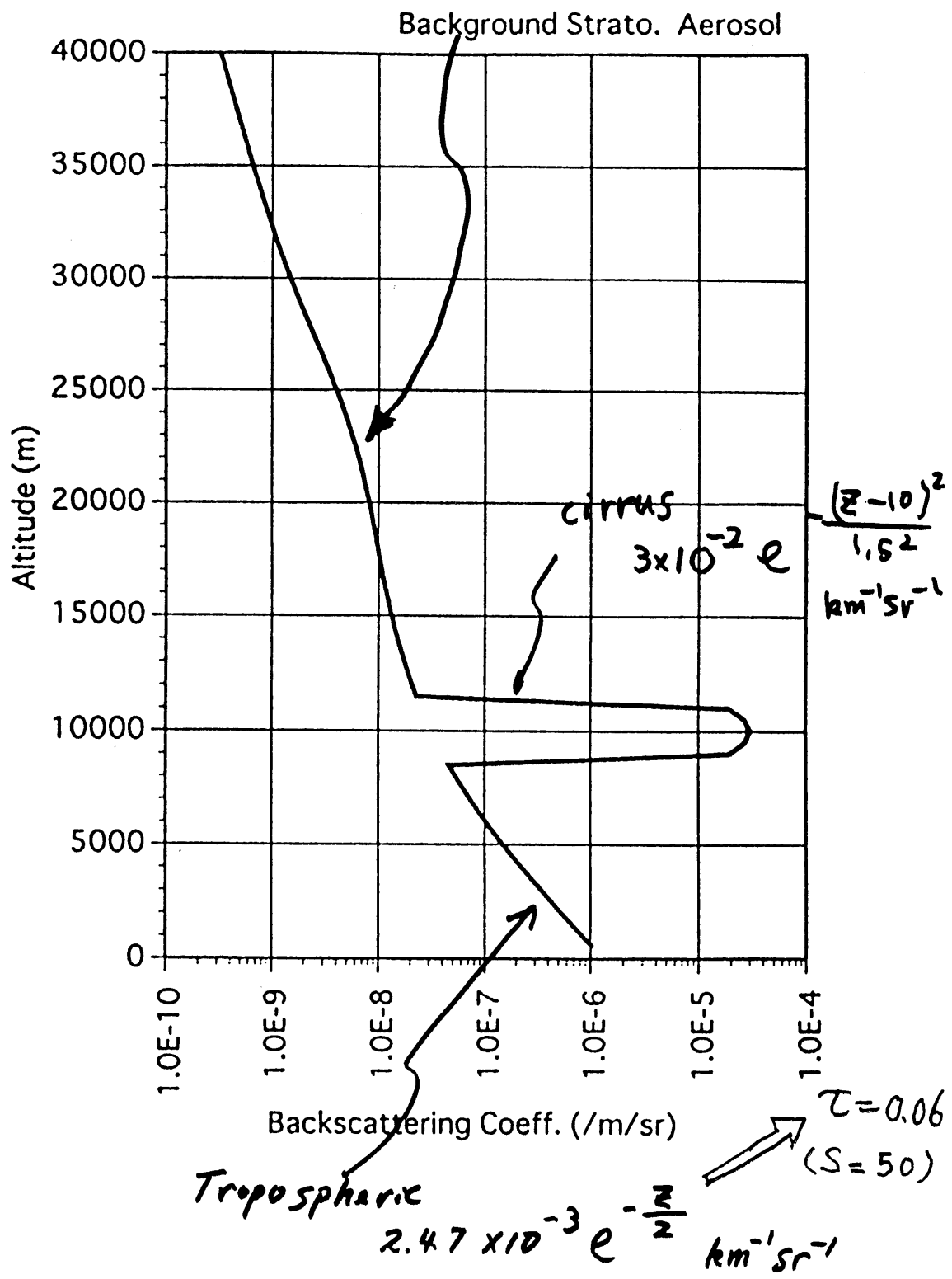
Objectives of ATOMS B1 Lidar

- (1) improvement of accuracy of the cirrus cloud thickness by adding capability for estimation multiple scattering
(multi- FOV receiver, D.L.Hutt et al., 1994),
- (2) depolarization measurement of the cirrus cloud and aerosol in nighttime,
- (3) daytime tropospheric aerosol measurement.

Lidar parameters

	1053nm	527nm	(1053nm)
Laser wavelength : λ	1053nm	527nm	(1053nm)
output energy : E	90mJ	4.4mJ	(50mJ)
repetition : (rep.)	100Hz		(100Hz)
average power : $W = E \times (\text{rep.})$	9W		(5W)
divergence : θ	0.15mrad		(0.1mrad)
Receiver			
Telescope : A	1m diameter		(1m diameter)
FOV : θ_r	0.19mrad		(0.1mrad)
Bandwidth : $\Delta\lambda$	0.3nm		(0.1nm)
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detector	Si-APD		(Si-APD)
quantum efficiency : η	0.36		(0.3)
	MDS Lidar		Feasibility Lidar

$$5.13 \times 10^{-6} e^{-\frac{(z-2)^2}{6^2}} \text{ km}^{-1} \text{ sr}^{-1}$$



Error of aerosol backscatter coefficient β_a

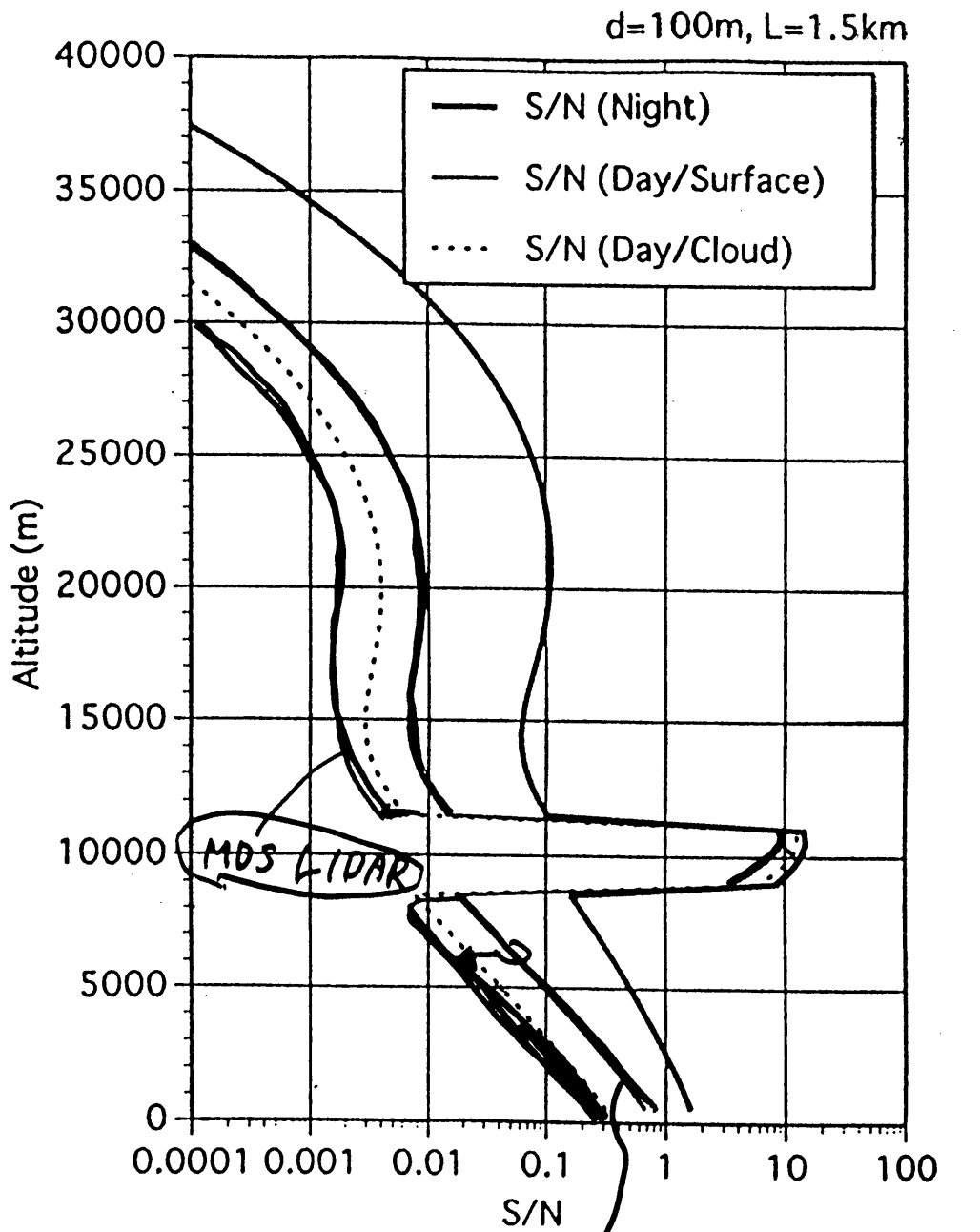
$$\delta\beta_a = \frac{\beta_a}{\sqrt{m} \left(\frac{S}{N} \right)} \quad m : \text{averaging number}$$

$$\left(\frac{S}{N} \right) \propto \left(\frac{S}{N} \right) \text{factor} = \frac{W \sqrt{T_0}}{\theta r \sqrt{\Delta\lambda} \frac{1}{\rho}}$$

$$\left(\frac{S}{N} \right) \text{factor} = 224 \quad \text{for Feasibility Lidar}$$

$$129 \quad \text{for MDS Lidar}$$

$$0.47 \times \left(\frac{S}{N} \right) \text{factor} \text{ of the Feasibility Lidar}$$



$$\left(\frac{S}{N}\right)_{\text{Feasibility}} = \frac{0.47}{0.58} \left(\frac{S}{N}\right)_{\text{MDS}}$$

Lidar parameters

Laser	wavelength : λ	1053nm	527nm	(1053nm)	1053nm
	output energy : E	90mJ	4.4mJ	(50mJ)	90mJ
	repetition : (rep.)	100Hz		(100Hz)	1 kHz
	average power : $W = E \times (\text{rep.})$	9W		(5W)	90W
	divergence : θ	0.15mrad		(0.1mrad)	0.1mrad
Receiver	Telescope : A	1m diameter		(1m diameter)	1m ϕ
	FOV : θ_r	0.19mrad		(0.1mrad)	0.1mrad
	Bandwidth : $\Delta\lambda$	0.3nm		(0.1nm)	0.01nm
	optical efficiency : T0	0.4		(0.5)	0.2
	detector	Si-APD		(Si-APD)	Si-APD
	quantum efficiency : η	0.36		(0.3)	0.36
		MDS		Feasibility	ATOMS B1

$$\left(\frac{S}{N}\right) \propto (S/N) \text{ factor} = \frac{W \sqrt{T_0}}{\theta_r \sqrt{\Delta\lambda}}$$

$$(S/N) \text{ factor} = 111 \text{ ~~224~~ for Feasibility Lidar}$$

$$52 \text{ ~~129~~ for MDS Lidar}$$

$$0.47 \text{ ~~0.056~~ } \times (S/N) \text{ factor of the Feasibility Lidar}$$

ATMOS B1 Lidar

$$(S/N) \text{ factor} = \frac{4,020}{20,120} \text{ for ATMOS B1 Lidar}$$

$$36 \text{ ~~90~~ } \times (S/N) \text{ factor of the Feasibility Lidar}$$

